

# VRAE-06E1A0 Series

## Non-Isolated DC-DC Converter

### MicroSIP Series

The Bel VRAE-06E1A Series is a part of the non-isolated DC/DC converter Power Module series. The modules use a SIP package. These converters are available in a range of output voltages from 0.59 to 5.1 VDC over a wide input voltage range 4.5 - 13.8 VDC. The efficiency is typically 91% at 3.3 Vout ( $V_{in} = 12$  VDC) at full load.



#### Key Features & Benefits

- Wide Input Voltage Range 4.5 VDC – 13.8 VDC
- 0.59 VDC – 5.1 VDC / 6 A Output
- Non-Isolated
- High Efficiency
- Fixed Frequency
- Low Cost
- Under-Voltage Lockout
- OCP/SCP
- Remote On/Off
- Class II, Category 2, Non-Isolated DC/DC Converter (refer to IPC-9592B)
- UL60950-1-2 2nd Edition Recognized (UL/cUL)



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## 1. MODEL SELECTION

PART NUMBER	OUTPUT VOLTAGE	INPUT VOLTAGE	MAX. OUTPUT CURRENT	MAX. OUTPUT POWER	TYPICAL EFFICIENCY
VRAE-06E1A0	0.59 VDC - 5.1 VDC	4.5 VDC - 13.8 VDC	6 A	30 W	91%

### PART NUMBER EXPLANATION

V	R	AE	-	06	E	1A	x	x
I Mount Type	RoHS	Series Name		Output Current	Input Range	Output Voltage	Suffix	Package
Vertical Mount	RoHS 6 Compliant	SIP		6 A	4.5 - 13.8 V	0.59 - 5.1 V	0 - Active High	G - Tray Packaging H - Tray packaging and RoHS compliant without requiring exemption 7c-III

## 2. ABSOLUTE MAXIMUM RATINGS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNITS
Input Supply Voltage		-0.3	-	15	V
Ambient Temperature		-40	-	85	°C
Storage Temperature		-55	-	125	°C
Altitude		-	-	2000	m

**NOTE:** All specifications are typical at 25 °C unless otherwise stated.

## 3. INPUT SPECIFICATIONS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Input Voltage	$V_o \leq 3.63$ V	4.5	-	13.8	V
	$V_o > 3.63$ V	7.0	-	13.8	
Input Current (Full load)	An input line fuse must always be used.	-	-	6	A
Input Current (No load)		-	50	100	mA
Remote Off Input Current		-	10	25	mA
Input Reflected Ripple Current (pk-pk)	With simulated source impedance of 1000 nH, 5 Hz to 20 MHz Use a 1000 $\mu$ F / 25 V AL-Cap with ESR = 0.03 ohm max and 2*100 $\mu$ F/25V Tan-Cap with ESR = 0.013 ohm max at 100 kHz @ 25°C.	-	80	150	mA
Input Reflected Ripple Current (rms)		-	25	50	mA
I <sup>2</sup> t Inrush Current Transient		-	-	1	A <sup>2</sup> s
Turn-on Voltage Threshold		4.15	4.3	4.45	V
Turn-off Voltage Threshold	A 30.1K resistor is connected from Enable to Vin	3.7	4.1	4.3	V

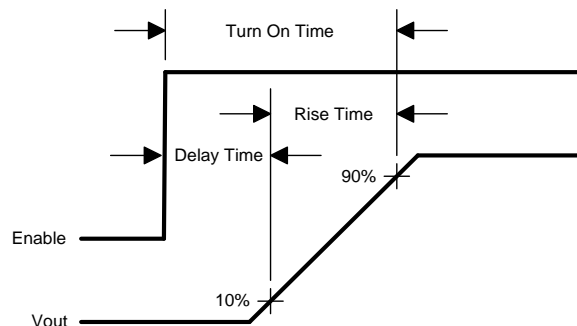
**NOTE:** All specifications are typical at 25 °C unless otherwise stated.

## 4. OUTPUT SPECIFICATIONS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Output Voltage Set Point Accuracy	Vin = 12 V, Iout = full load	-2	-	+2	% Vo, set
Load Regulation		-	±0.3	±1	% Vo, set
Line Regulation		-	±0.3	±1	% Vo, set
Regulation Over Temperature		-	0.3	0.5	% Vo, set
Output Current		0	-	6	A
Output DC Current Limit		7.2	9	12	A
Output Ripple and Noise (pk-pk)	0 – 20 MHz BW, with a 1 µF ceramic capacitor and a 10 µF tantalum cap at output.	-	50	70	mV
Output Ripple and Noise (rms)		-	15	25	mV
Short Circuit Surge Transient		-	-	5	A²s
Turn-on Time <sup>1</sup>	Vout = 5.0V; time from enable going high to 90% of Vout	1	-	3	ms
	Vout = 3.3V; time from enable going high to 90% of Vout	1	-	3	ms
	Vout = 1.8V; time from enable going high to 90% of Vout	1	-	3	ms
	Vout = 0.9V; time from enable going high to 90% of Vout	1	-	3	ms
Rise Time <sup>1</sup>	Vout = 5.0V; time from 10% to 90% of Vout	-	1.3	1.8	ms
	Vout = 3.3V; time from 10% to 90% of Vout	-	1.3	1.8	ms
	Vout = 1.8V; time from 10% to 90% of Vout	-	1.3	1.8	ms
	Vout = 0.9V; time from 10% to 90% of Vout	-	1.3	1.8	ms
Overshoot at Turn-on		-	-	1	%
Output Capacitance		0	-	1000	µF
TRANSIENT RESPONSE					
50% ~ 100% Max Load		-	200	250	mV
Settling Time	di/dt = 2.5 A/µS; Vin =12 V; with 10 µF tantalum cap and 1 µF ceramic at the output, Ta=25 °C	-	20	50	µs
100% ~ 50% Max Load		-	200	250	mV
Settling Time		-	20	50	µs

<sup>1</sup> The turn on time is guaranteed to be in between the minimum and maximum limits specified over all operating temperatures. Output capacitance used was 1x 1000 µF aluminum, 1x 10 µF tantalum, and 1x 1 µF ceramic. The turn on waveform with parameter measurement locations is shown below.

**NOTE:** All specifications are typical at normal input, full load at Ta= 25°C unless otherwise stated.



## 5. GENERAL SPECIFICATIONS

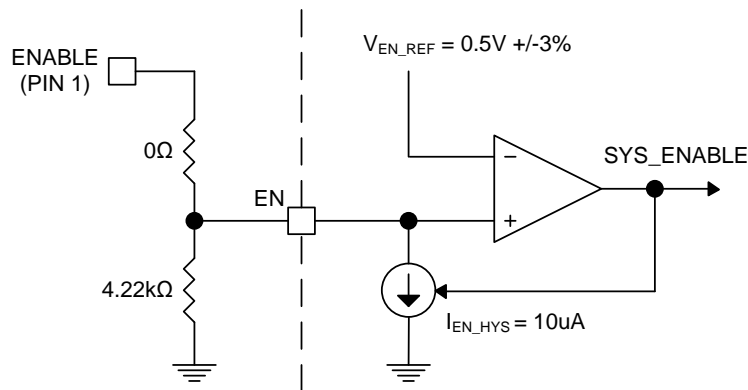
PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Efficiency	$V_o = 5.0\text{ V}$	91	93	-	%
	$V_o = 3.3\text{ V}$	89	91	-	
	$V_o = 2.5\text{ V}$	85	87	-	
	$V_o = 1.8\text{ V}$	82	84	-	
	$V_o = 1.5\text{ V}$	80	82	-	
	$V_o = 1.2\text{ V}$	77	79	-	
	$V_o = 0.9\text{ V}$	72	74	-	
Switching Frequency		-	500	-	kHz
Output Voltage Trim Range	Wide Trim	0.591	-	5.1	V
MTBF	Calculated Per Bell Core SR-332 ( $I_o = 80\%$ load; $V_{in} = 12\text{ V}$ ; $V_o = 5\text{ V}$ ; 200 LFM; $T_a = 25\text{ }^\circ\text{C}$ )		8 440 749		h
Weight		-	2.2	-	g
Dimensions (L x W xH)		0.65 x 0.41 x 0.295			in
		16.51 x 10.41 x 7.50			mm

**NOTE:** All specifications are typical at 25 °C unless otherwise stated.

## 6. CONTROL SPECIFICATIONS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
<b>Remote On/Off (Active High)</b>					
Turn On Voltage Threshold	Unit is on when voltage on enable pin is driven above the turn on threshold. When enable pin is floating, unit is off.	0.485	0.500	0.515	V
Maximum Enable Voltage	Maximum voltage that should be applied to the enable pin.	-	-	5.5	V
Hysteresis Source Current	A 10 $\mu\text{A}$ current source to GND ( $I_{EN\_HYS}$ ) is active when unit is off and inactive when unit is on (see figure below).	7.5	10	11.5	$\mu\text{A}$

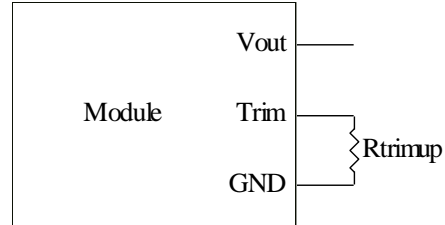
**NOTE:** The following figure shows the internal circuitry for the enable.



## 7. OUTPUT TRIM EQUATIONS

Equation for calculating the trim resistor given the desired output voltage (Vo) is shown below. The Rtrim resistor should be connected between the trim pin and GND pin.

$$R_{trim} = \frac{1.182}{V_o - 0.591} k\Omega$$



## 8. RIPPLE AND NOISE WAVEFORM

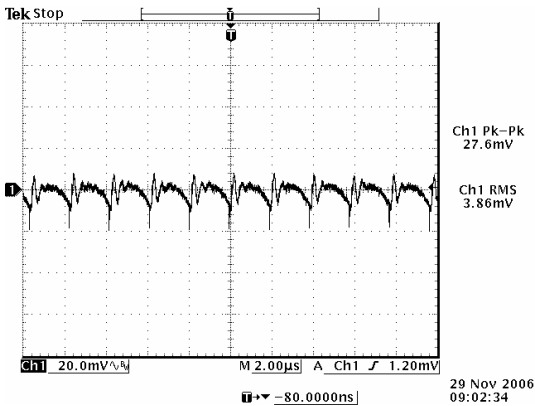


Figure 6. 12 V input, 0.591 V output

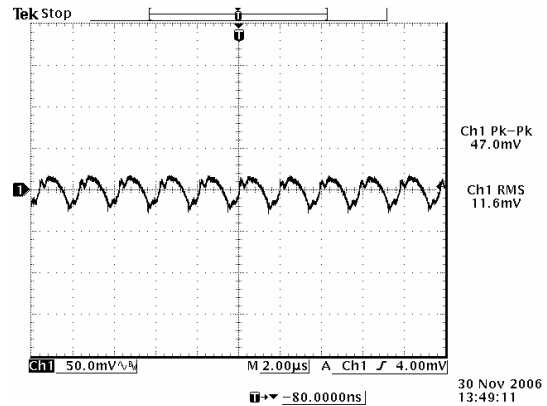


Figure 7. 12 V input, 3.3 V output.

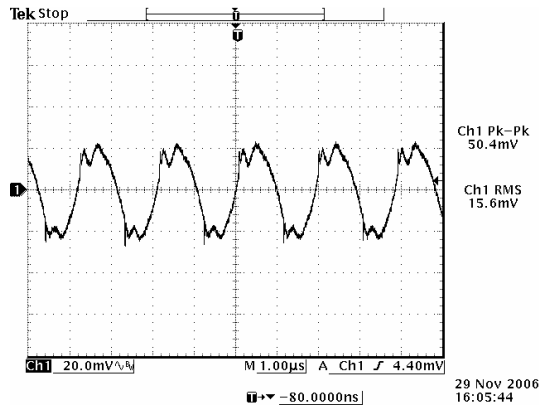
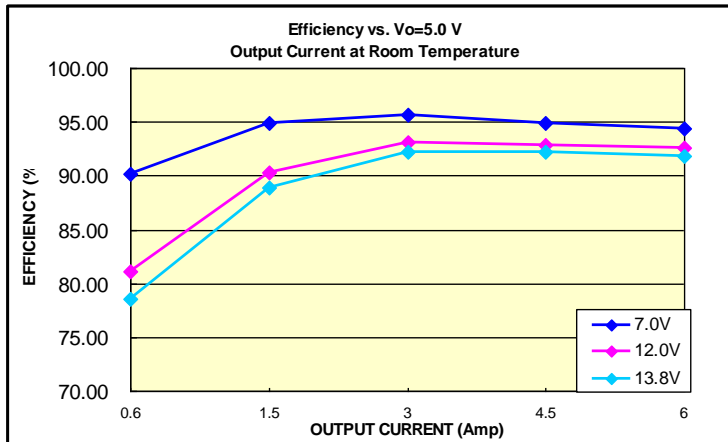
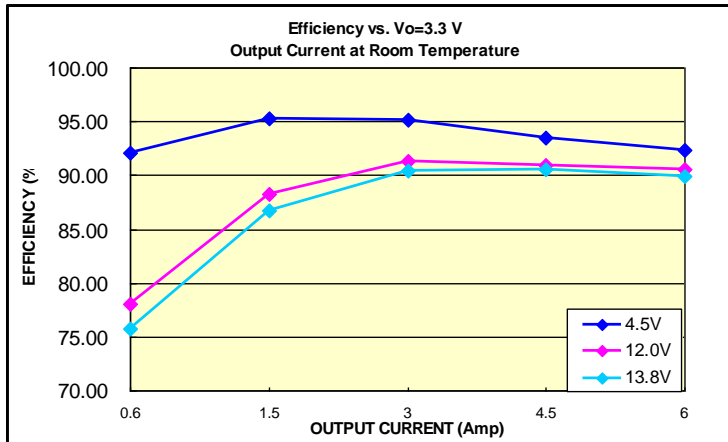
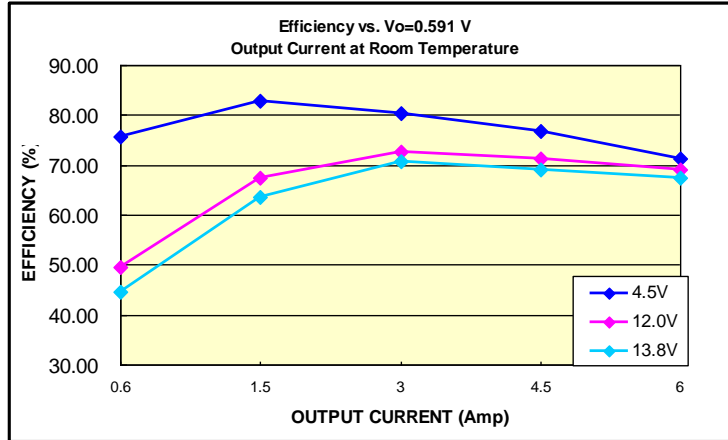


Figure 8. 12 V input, 5.0 V output.

**NOTE:** Ripple and noise at full load, 0-20 MHz BW, with a 1 µF ceramic cap and a 10 µF tantalum cap, and Ta=25 °C.

9. EFFICIENCY DATA



## 10. THERMAL DERATING CURVES

The thermal reference point  $T_{ref}$  is shown below. For reliable operation this temperature should not exceed 115 °C. The output power of the module should not exceed the rated power for the module.

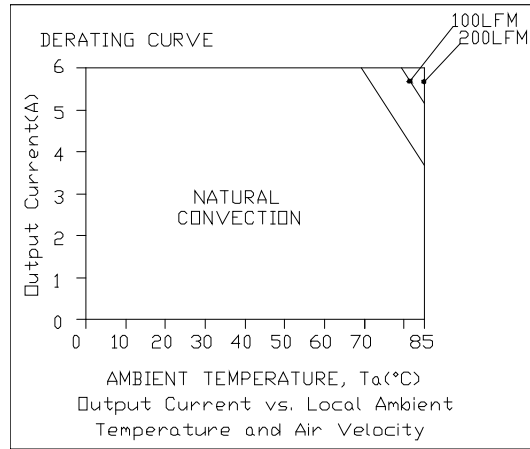
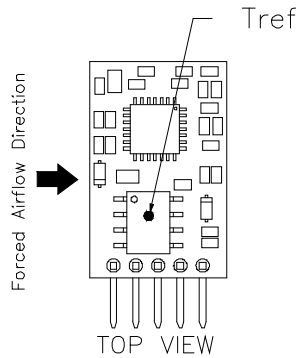


Figure 1.  $V_{in}=12\text{ V}$ ,  $V_{out} = 5\text{ V}$

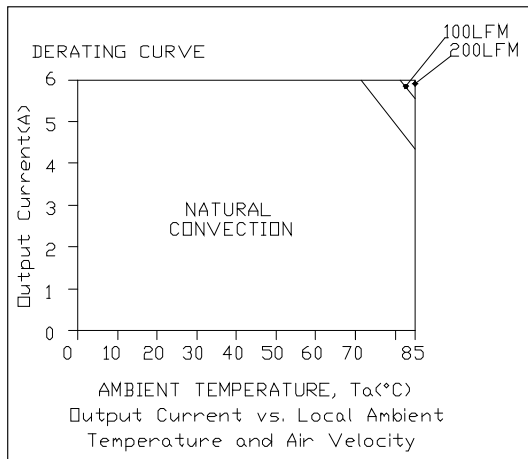


Figure 2.  $V_{in}=12\text{ V}$ ,  $V_{out} = 3.3\text{ V}$

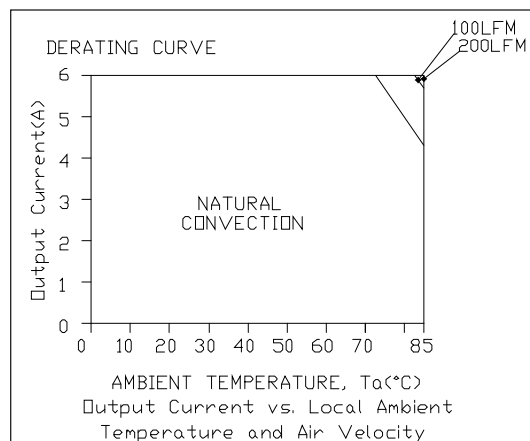


Figure 3.  $V_{in}=12\text{ V}$ ,  $V_{out} = 2.5\text{ V}$

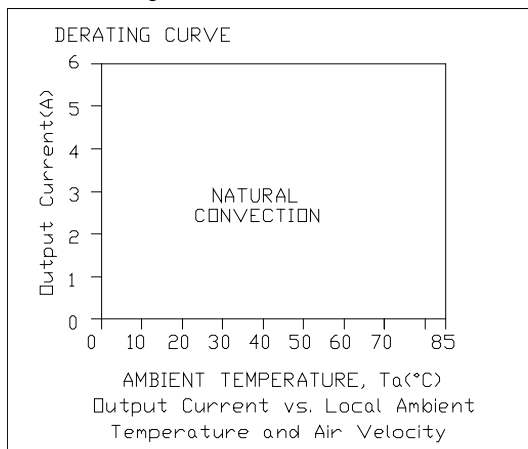


Figure 4.  $V_{in}=12\text{ V}$ ,  $V_{out} = 1.2\text{ V}$

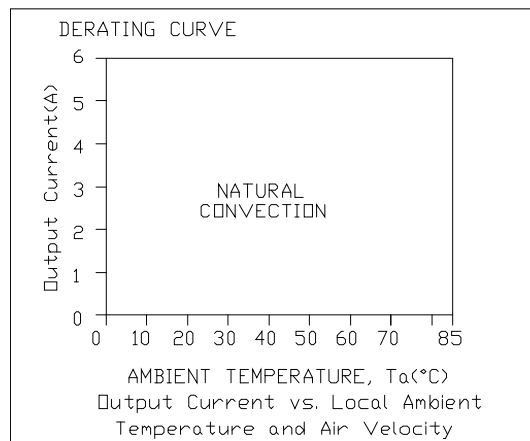


Figure 5.  $V_{in}=12\text{ V}$ ,  $V_{out} = 0.59\text{ V}$

11. TRANSIENT RESPONSE WAVEFORMS

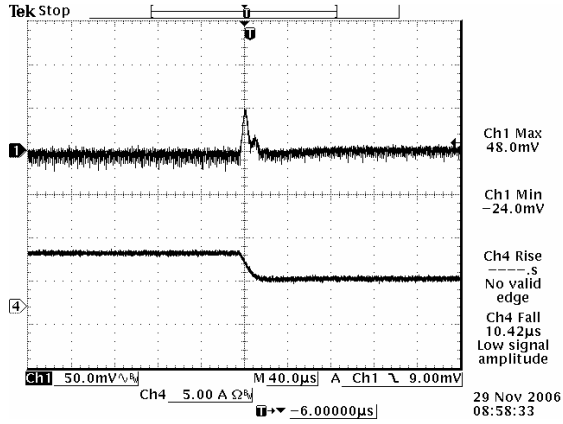


Figure 9. 100% to 50% load step at 12 V input, 0.591 V output

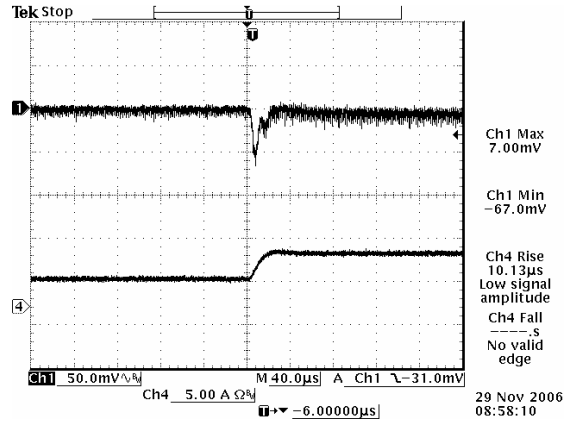


Figure 10. 50% to 100% load step at 12 V input, 0.591 V output

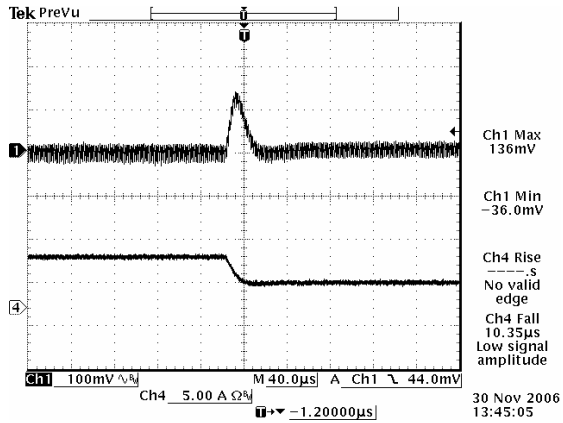


Figure 11. 100% to 50% load step at 12 V input, 3.3 V output

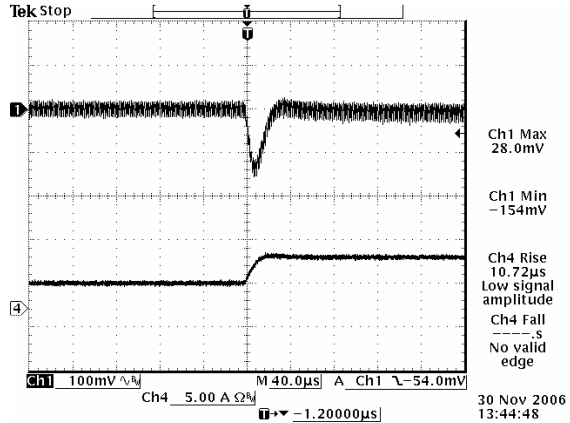


Figure 12. 50% to 100% load step at 12 V input, 3.3 V output

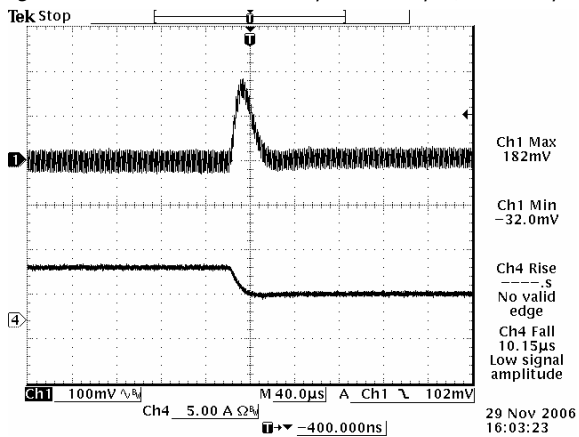


Figure 13. 100% to 50% load step at 12 V input, 5.0 V output

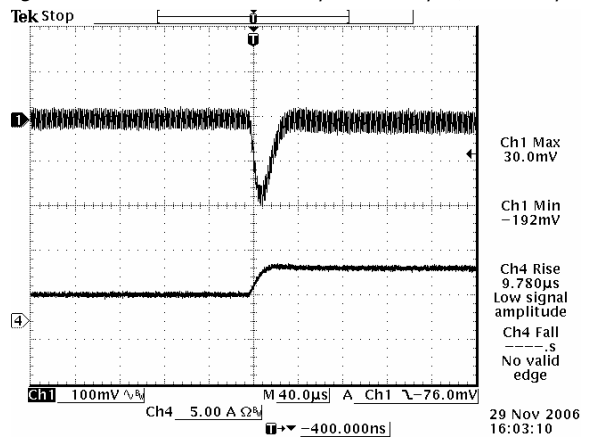
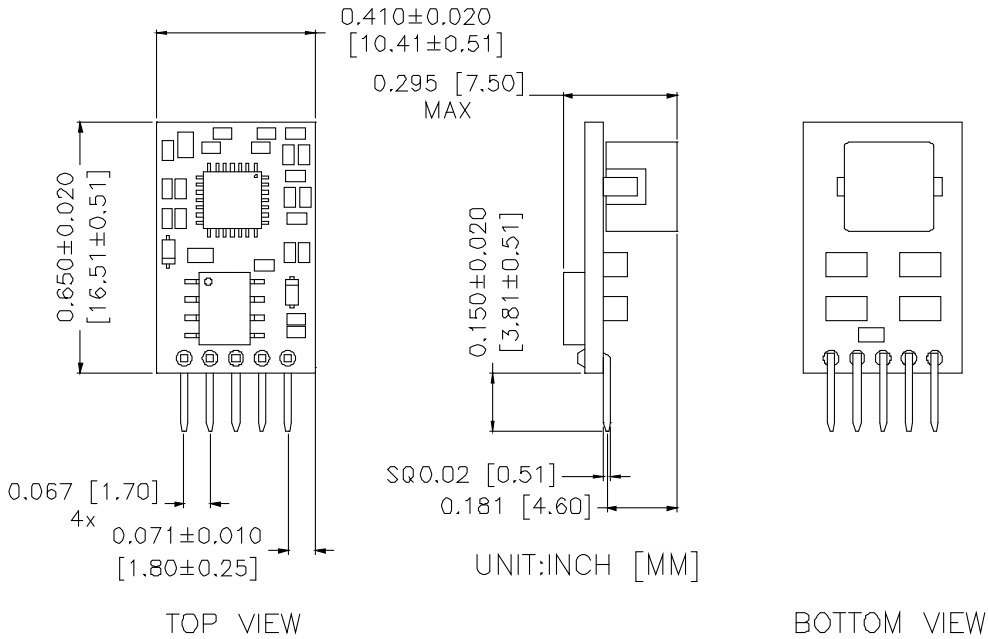


Figure 14. 50% to 100% load step at 12 V input, 5.0 V output

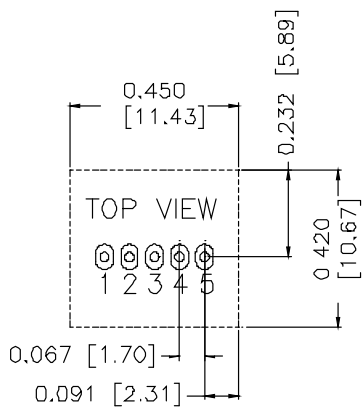
**NOTE:** Transient response at  $di/dt=0.25 \text{ A}/\mu\text{s}$ , with a  $1\mu\text{F}$  ceramic cap and a  $10\mu\text{F}$  tantalum cap at the output, and  $T_a=25^\circ \text{ C}$ .



## 12. MECHANICAL OUTLINE



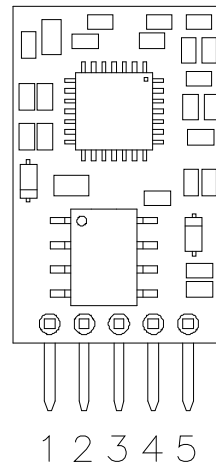
### RECOMMENDED PAD LAYOUT



PAD: LENGTH 0.067 [ø1.7] BOTH SIDE  
 WIDTH 0.047 [ø1.2] BOTH SIDE  
 HOLE: ø0.035 [ø0.89] BOTH SIDE

### PIN CONNECTIONS

PIN	NAME
1	ENABLE
2	Vin
3	GND
4	Vout
5	Trim



**NOTE:** This module is recommended and compatible with Pb-Free Wave Soldering and must be soldered using a peak solder temperature of no more than 260°C for less than 5 seconds.

#### NOTES:

- 1) All Pins: Material - Copper Alloy;  
 Finish - 3 micro inches minimum Gold over 50 micro inches minimum Nickel plate.
- 2) Undimensioned components are shown for visual reference only.
- 3) All dimensions in inches (mm); Tolerances: x.xx +/-0.02 in[0.5mm]. x.xxx +/-0.010 in[0.25mm].

### 13. ASSEMBLY NOTE

Modules were designed for vertical insertion into host board. Experiments should be performed to make sure that the units meet the intended tilt specification. A fixture may be needed to make the module stand upright in assembly.

### 14. REVISION HISTORY

DATE	REVISION	CHANGE DESCRIPTION	APPROVAL
2010-04-22	G	1. Change operating temp range from 0~70 °C to -40~85 °C 2. Add the data of full load input current	XF JIANG
2013-05-16	H	1. Update Output Specifications 2. Update control Specifications	XF JIANG
2015-12-28	I	Add Assembly Note. Update mechanical drawing	XF JIANG
2017-12-15	J	Datasheet updated to the new Bel template	

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